

# Sharpness aware minimization

Axel Böhm

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## SHARPNESS-AWARE MINIMIZATION FOR EFFICIENTLY IMPROVING GENERALIZATION

Pierre Foret \*

Google Research  
pierreforet@google.com

Ariel Kleiner

Google Research  
akleiner@google.com

Hossein Mobahi

Google Research  
hmobahi@google.com

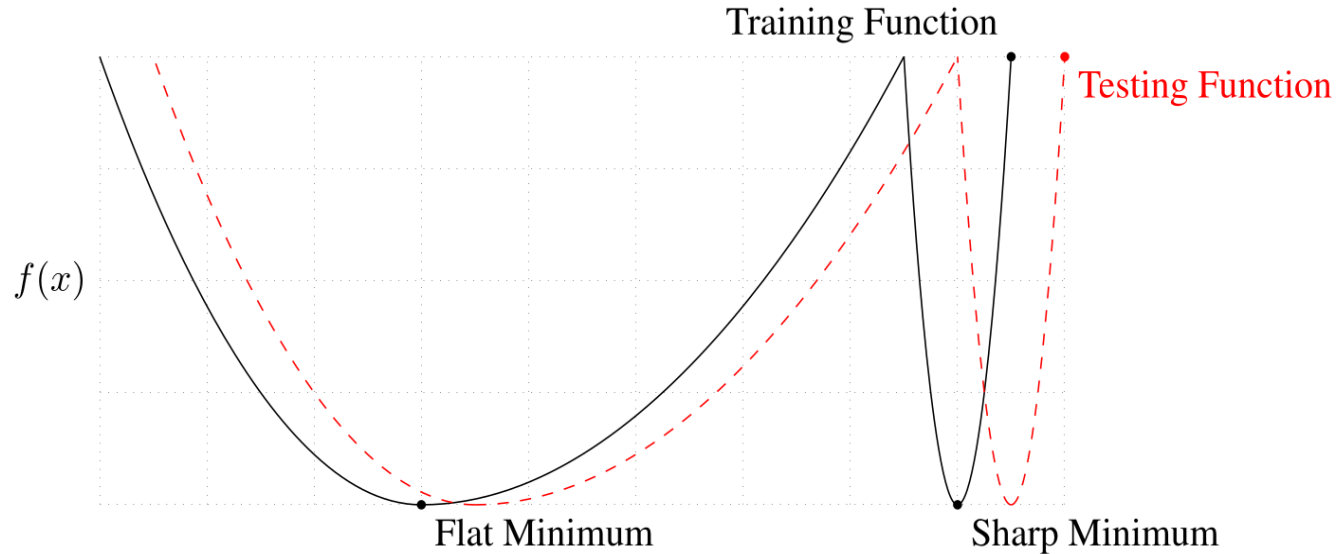
Behnam Neyshabur

Blueshift, Alphabet  
neyshabur@google.com

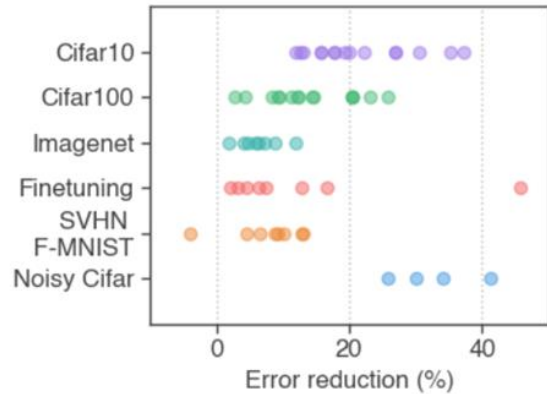
In today's heavily overparameterized models, the value of the training loss provides few guarantees on model generalization ability. Indeed, optimizing only the training loss value, as is commonly done, can easily lead to suboptimal model quality. Motivated by prior work connecting the geometry of the loss landscape and generalization, we introduce a novel, effective procedure for instead simultaneously minimizing loss value and loss sharpness. In particular, our procedure, Sharpness-Aware Minimization (SAM), seeks parameters that lie in neighborhoods having uniformly low loss; this formulation results in a min-

# Why flatness?

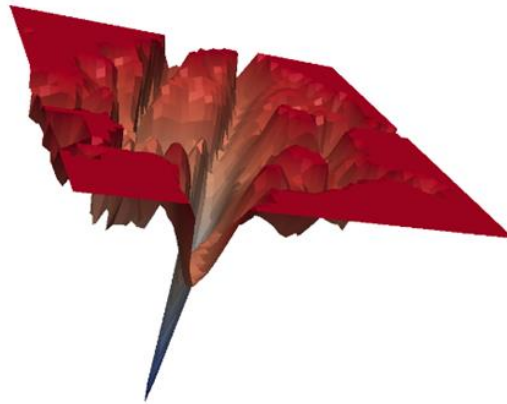
- .description length
- .Free Gibbs energy
- .Bayesian learning
- .Intuition (r.h.s.)



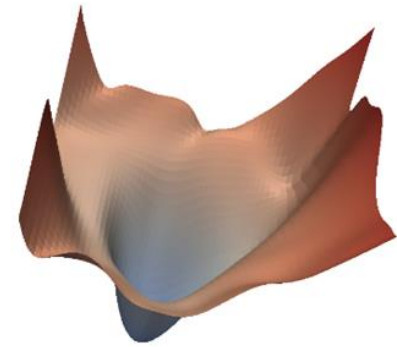
# Extensive empirical evaluation



Error rate reduction obtained by switching to SAM. Each point is a different dataset / model / data augmentation



A sharp minimum to which a ResNet trained with SGD converged



A wide minimum to which the same ResNet trained with SAM converged.

# The motivation

**Theorem (stated informally) 1.** For any  $\rho > 0$ , with high probability over training set  $\mathcal{S}$  generated from distribution  $\mathcal{D}$ ,

$$L_{\mathcal{D}}(\mathbf{w}) \leq \max_{\|\boldsymbol{\epsilon}\|_2 \leq \rho} L_{\mathcal{S}}(\mathbf{w} + \boldsymbol{\epsilon}) + h(\|\mathbf{w}\|_2^2 / \rho^2),$$

•PAC-Bayes (Probably Approximately Correct '84)

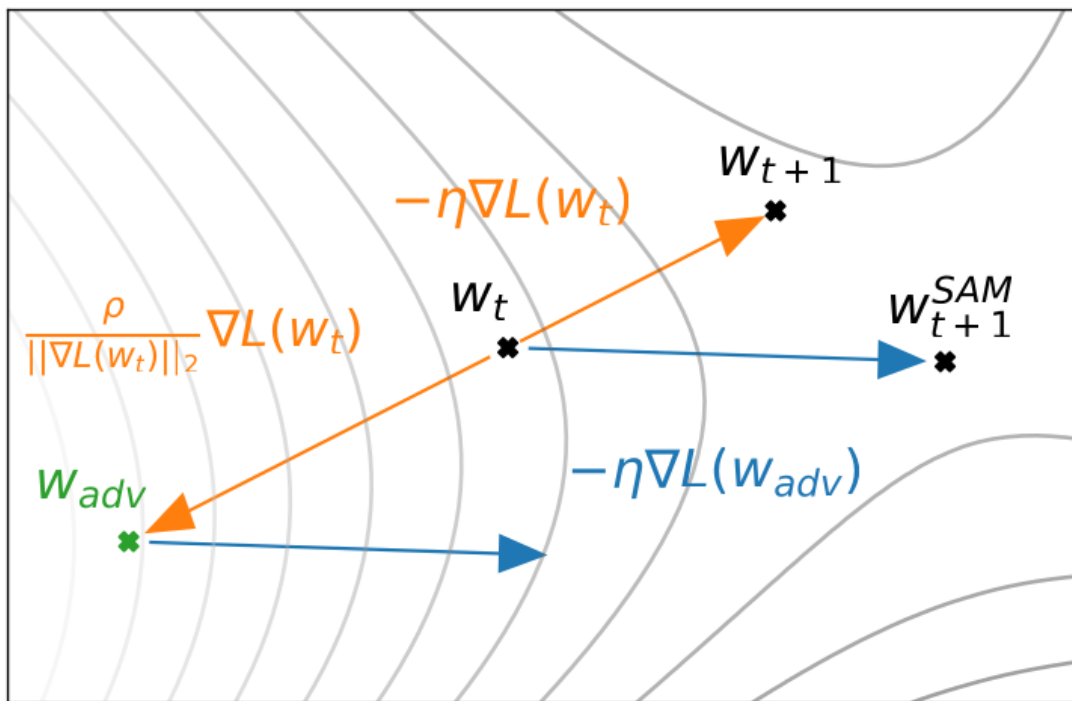
•Minimize the r.h.s. instead:

$$\min_{\mathbf{w}} L_{\mathcal{S}}^{SAM}(\mathbf{w}) + \lambda \|\mathbf{w}\|_2^2 \quad \text{where} \quad L_{\mathcal{S}}^{SAM}(\mathbf{w}) \triangleq \max_{\|\boldsymbol{\epsilon}\|_p \leq \rho} L_{\mathcal{S}}(\mathbf{w} + \boldsymbol{\epsilon}),$$

# The algorithm

$$x(t+1) = x(t) - \eta \nabla L \left( x + \rho \frac{\nabla L(x)}{\|\nabla L(x)\|_2} \right)$$

$$\epsilon^*(\mathbf{w}) \triangleq \arg \max_{\|\epsilon\|_p \leq \rho} L_S(\mathbf{w} + \epsilon) \approx \arg \max_{\|\epsilon\|_p \leq \rho} L_S(\mathbf{w}) + \epsilon^T \nabla_{\mathbf{w}} L_S(\mathbf{w}) = \arg \max_{\|\epsilon\|_p \leq \rho} \epsilon^T \nabla_{\mathbf{w}} L_S(\mathbf{w}).$$



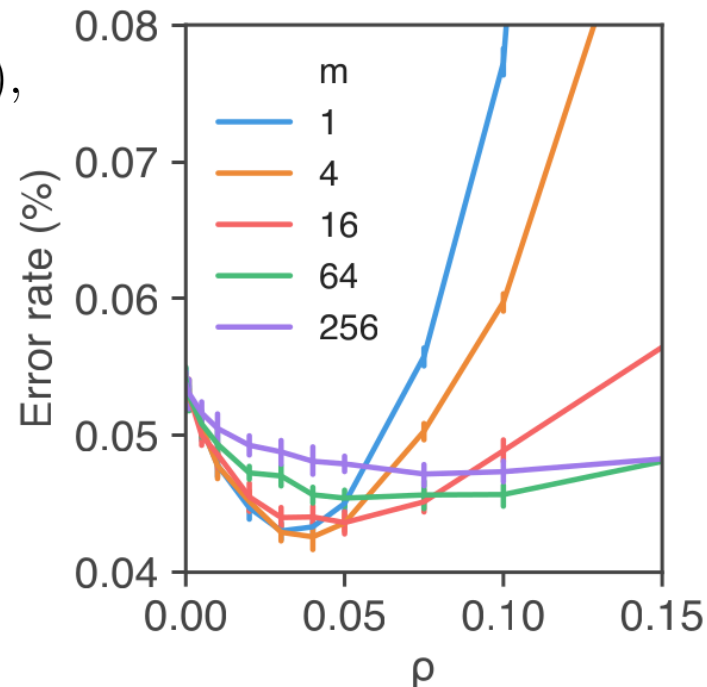
# In implementation: mSAM

Though our derivation of SAM defines the SAM objective over the entire training set, when utilizing SAM in practice, we compute the SAM update per-batch (as described in Algorithm 1) or even by averaging SAM updates computed independently per-accelerator (where each accelerator receives a

$$\nabla \mathcal{L}_{\mathcal{S}}^{mSAM}(w) = \frac{1}{m} \sum_{i=1}^m \nabla \mathcal{L}_{\mathcal{S}_i}(w + \rho \nabla \mathcal{L}_{\mathcal{S}_i}(w) / \|\nabla \mathcal{L}_{\mathcal{S}_i}(w)\|_2),$$

smaller values of  $m$  tend to yield models

having better generalization ability.



# Better understanding

## How Does Sharpness-Aware Minimization Minimize Sharpness?

Kaiyue Wen

Tsinghua University

wenky20@mails.tsinghua.edu.cn

Tengyu Ma

Stanford University

tengyuma@stanford.edu

Zhiyuan Li

Stanford University

zhiyuanli@stanford.edu

theoretical characterizations. SAM intends to penalize a notion of sharpness of the model but implements a computationally efficient variant; moreover, a third notion of sharpness was used for proving generalization guarantees. The subtle differences in these notions of sharpness can

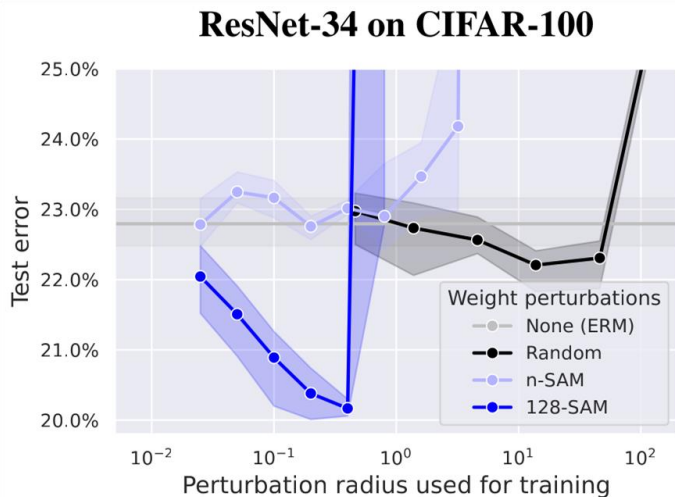
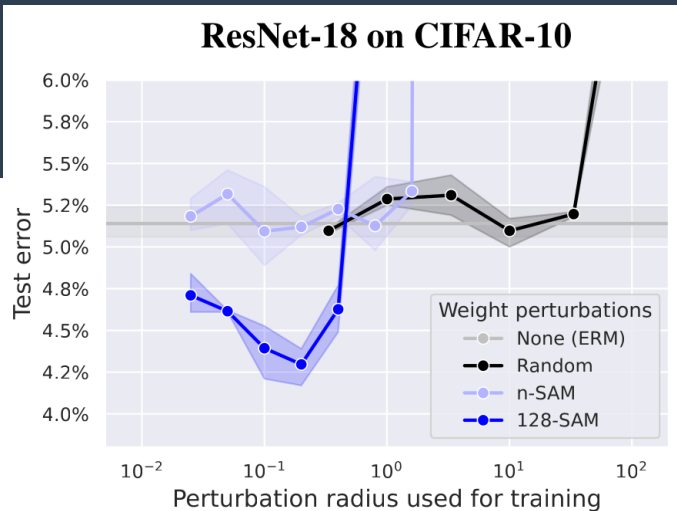
Type of Sharpness-Aware Loss	Notation	Definition	Biases (among minimizers)
Worst-direction	$L_\rho^{\text{Max}}$	$\max_{\ v\ _2 \leq 1} L(x + \rho v)$	$\min_x \lambda_1(\nabla^2 L(x))$ (Thm E.3)
Ascent-direction	$L_\rho^{\text{Asc}}$	$L\left(x + \rho \frac{\nabla L(x)}{\ \nabla L(x)\ _2}\right)$	$\min_x \lambda_{\min}(\nabla^2 L(x))$ (Thm E.4)
Average-direction	$L_\rho^{\text{Avg}}$	$\mathbb{E}_{g \sim N(0, I)} L\left(x + \rho \frac{g}{\ g\ _2}\right)$	$\min_x \text{Tr}(\nabla^2 L(x))$ (Thm E.5)



# Towards Understanding Sharpness-Aware Minimization

Maksym Andriushchenko<sup>1</sup> Nicolas Flammarion<sup>1</sup>

The existing generalization bound does not explain the success of SAM. The main theoretical justification for SAM comes from the PAC-Bayesian generalization bound presented, e.g., in Theorem 2 of Foret et al. (2021). However, the bound is derived for *random* perturbations of the parameters, i.e. the leading term of the bound is  $\mathbb{E}_{\delta \sim \mathcal{N}(0, \sigma)} \sum_{i=1}^n \ell_i(w + \delta)$ . The extension to *worst-case* perturbations, i.e.  $\max_{\|\delta\|_2 \leq \rho} \sum_{i=1}^n \ell_i(w + \delta)$ , is done post hoc and only makes the bound less tight. Moreover, we can see empirically (Fig. 1) that *both* training methods suggested by the derivation of this bound (random perturbations and *n*-SAM) do not substantially improve generalization. This



# Related literature: A concurrent work

## Regularizing Neural Networks via Adversarial Model Perturbation

Yaowei Zheng  
BDBC and SKLSDE  
Beihang University, China  
hiyouga@buaa.edu.cn

Richong Zhang\*  
BDBC and SKLSDE  
Beihang University, China  
zhangrc@act.buaa.edu.cn

Yongyi Mao  
School of EECS  
University of Ottawa, Canada  
ymao@uottawa.ca

larization techniques (*e.g.*, [10, 22, 23, 44]). A concurrent work of [9] further provides a PAC-Bayesian justification as to why the flatness of the minima helps generalization.

$$\mathcal{L}_{\text{AMP}}(\boldsymbol{\theta}) := \max_{\Delta: \|\Delta\| \leq \epsilon} \mathcal{L}_{\text{ERM}}(\boldsymbol{\theta} + \Delta)$$

# The prequel

• Basically SAM for adversarial training

• Predates all other papers

## Adversarial Weight Perturbation Helps Robust Generalization

Dongxian Wu<sup>1,3</sup>   Shu-Tao Xia<sup>1,3</sup>   Yisen Wang<sup>2†</sup>

<sup>1</sup>Tsinghua University

<sup>2</sup>Key Lab. of Machine Perception (MoE), School of EECS, Peking University

<sup>3</sup>PCL Research Center of Networks and Communications, Peng Cheng Laboratory

### Abstract

The study on improving the robustness of deep neural networks against adversarial examples grows rapidly in recent years. Among them, **adversarial training** is the most promising one, which flattens the **input loss landscape** (loss change with respect to input) via training on adversarially perturbed examples. However, how the widely used **weight loss landscape** (loss change with respect to weight) performs **in adversarial training** is rarely explored. In this paper, we investigate the weight loss landscape from a new perspective, and identify a clear correlation between the **flatness of weight loss landscape and robust generalization gap**. Several well-recognized adversarial training improvements, such as early stopping, designing new objective functions, or leveraging unlabeled data, all implicitly flatten the weight loss landscape. Based on these observations, we propose a simple yet effective **Adversarial Weight Perturbation (AWP)** to explicitly regularize the flatness of weight loss landscape, forming a *double-perturbation* mechanism in the

# Generalization

**Sharpness and Generalization.** The study on the connection between sharpness and generalization can be traced back to Hochreiter & Schmidhuber (1997). Keskar et al. (2016) observe a positive correlation between the batch size, the generalization error, and the sharpness of the loss landscape when changing the batch size. Jastrzebski et al. (2017) extend this by finding a correlation between the sharpness and the ratio between learning rate to batch size. Dinh et al. (2017) show that one can easily construct networks with good generalization but with arbitrary large sharpness by reparametrization. Dziugaite & Roy (2017); Neyshabur et al. (2017); Wei & Ma (2019a,b) give theoretical guarantees on the generalization error using sharpness-related measures. Jiang et al. (2019) perform a large-scale empirical study on various generalization measures and show that sharpness-based measures have the highest correlation with generalization.

# SAM

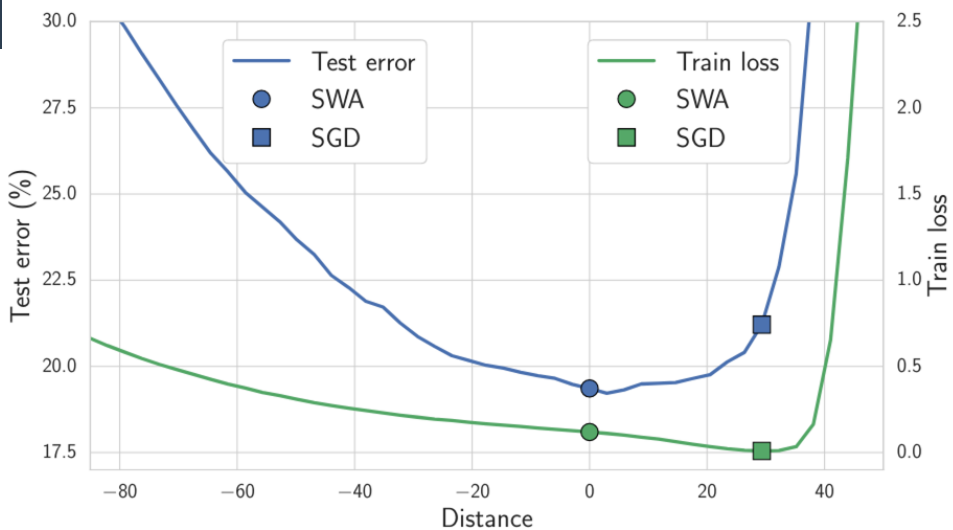
- .Improve generalization via flatness
- .Easy to implement, only 1.5x slower
- .Many approximations / engineering
- .Little understanding
- .Useful in (semi)-supervised / adversarial learning, noisy labels, ...



**Questions?**

# Bonus

## Averaging Weights Leads to Wider Optima and Better Generalization



**Pavel Izmailov**\*<sup>1</sup>

**Dmitrii Podoprikin**\*<sup>2,3</sup> **Timur Garipov**\*<sup>4,5</sup> **Dmitry Vetrov**<sup>2,3</sup> **Andrew Gordon Wilson**<sup>1</sup>  
<sup>1</sup>Cornell University, <sup>2</sup>Higher School of Economics, <sup>3</sup>Samsung-HSE Laboratory,  
<sup>4</sup>Samsung AI Center in Moscow, <sup>5</sup>Lomonosov Moscow State University

